

```

//Gauss Elimination
#include<iostream>
#include<iomanip>
using namespace std;
int main()
{
    int n,i,j,k;
    cout.precision(4);          //set precision
    cout.setf(ios::fixed);
    cout<<"\nEnter the no. of equations\n";
    cin>>n;                      //input the no. of equations
    float a[n][n+1],x[n];      //declare an array to store the elements of augmented-
matrix
    cout<<"\nEnter the elements of the augmented-matrix row-wise:\n";
    for (i=0;i<n;i++)
        for (j=0;j<=n;j++)
            cin>>a[i][j];      //input the elements of array
    for (i=0;i<n;i++)          //Pivotisation
        for (k=i+1;k<n;k++)
            if (abs(a[i][i])<abs(a[k][i]))
                for (j=0;j<=n;j++)
                {
                    double temp=a[i][j];
                    a[i][j]=a[k][j];
                    a[k][j]=temp;
                }
    cout<<"\nThe matrix after Pivotisation is:\n";
    for (i=0;i<n;i++)          //print the new matrix
    {
        for (j=0;j<=n;j++)
            cout<<a[i][j]<<setw(16);
        cout<<"\n";
    }
    for (i=0;i<n-1;i++)        //loop to perform the gauss elimination
        for (k=i+1;k<n;k++)
        {
            double t=a[k][i]/a[i][i];
            for (j=0;j<=n;j++)
                a[k][j]=a[k][j]-t*a[i][j];    //make the elements below the pivot
elements equal to zero or eliminate the variables
        }
    cout<<"\n\nThe matrix after gauss-elimination is as follows:\n";
    for (i=0;i<n;i++)          //print the new matrix
    {
        for (j=0;j<=n;j++)
            cout<<a[i][j]<<setw(16);
        cout<<"\n";
    }
    for (i=n-1;i>=0;i--)      //back-substitution
    {
        //x is an array whose values correspond to the values of
x,y,z..

```

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    x[i]=a[i][n];           //make the variable to be calculated equal to the
rhs of the last equation
    for (j=i+1;j<n;j++)
        if (j!=i)         //then subtract all the lhs values except the
coefficient of the variable whose value           is being
calculated
            x[i]=x[i]-a[i][j]*x[j];
    x[i]=x[i]/a[i][i];     //now finally divide the rhs by the coefficient
of the variable to be calculated
}
cout<<"\nThe values of the variables are as follows:\n";
for (i=0;i<n;i++)
    cout<<x[i]<<endl;     // Print the values of x, y,z,....
return 0;
}

```

The matrix after Pivotisation is:

6.0000	1.0000	-6.0000	-5.0000	6.0000
0.0000	2.0000	0.0000	1.0000	0.0000
2.0000	2.0000	3.0000	2.0000	-2.0000
4.0000	-3.0000	0.0000	1.0000	-7.0000

The matrix after gauss-elimination is as follows:

6.0000	1.0000	-6.0000	-5.0000	6.0000
0.0000	2.0000	0.0000	1.0000	0.0000
0.0000	0.0000	5.0000	2.8333	-4.0000
0.0000	0.0000	-0.0000	3.9000	-7.8000

The values of the variables are as follows:

```

-0.5000
1.0000
0.3333
-2.0000

```

Sample 1

```
The matrix after Pivotisation is:
4.0000      -2.0000      1.0000      15.0000
-3.0000     -1.0000      4.0000      8.0000
1.0000      -1.0000      3.0000     13.0000

The matrix after gauss-elimination is as follows:
4.0000      -2.0000      1.0000     15.0000
0.0000     -2.5000      4.7500     19.2500
0.0000      0.0000      1.8000      5.4000

The values of the variables are as follows:
2.0000
-2.0000
3.0000
```

Sample 2

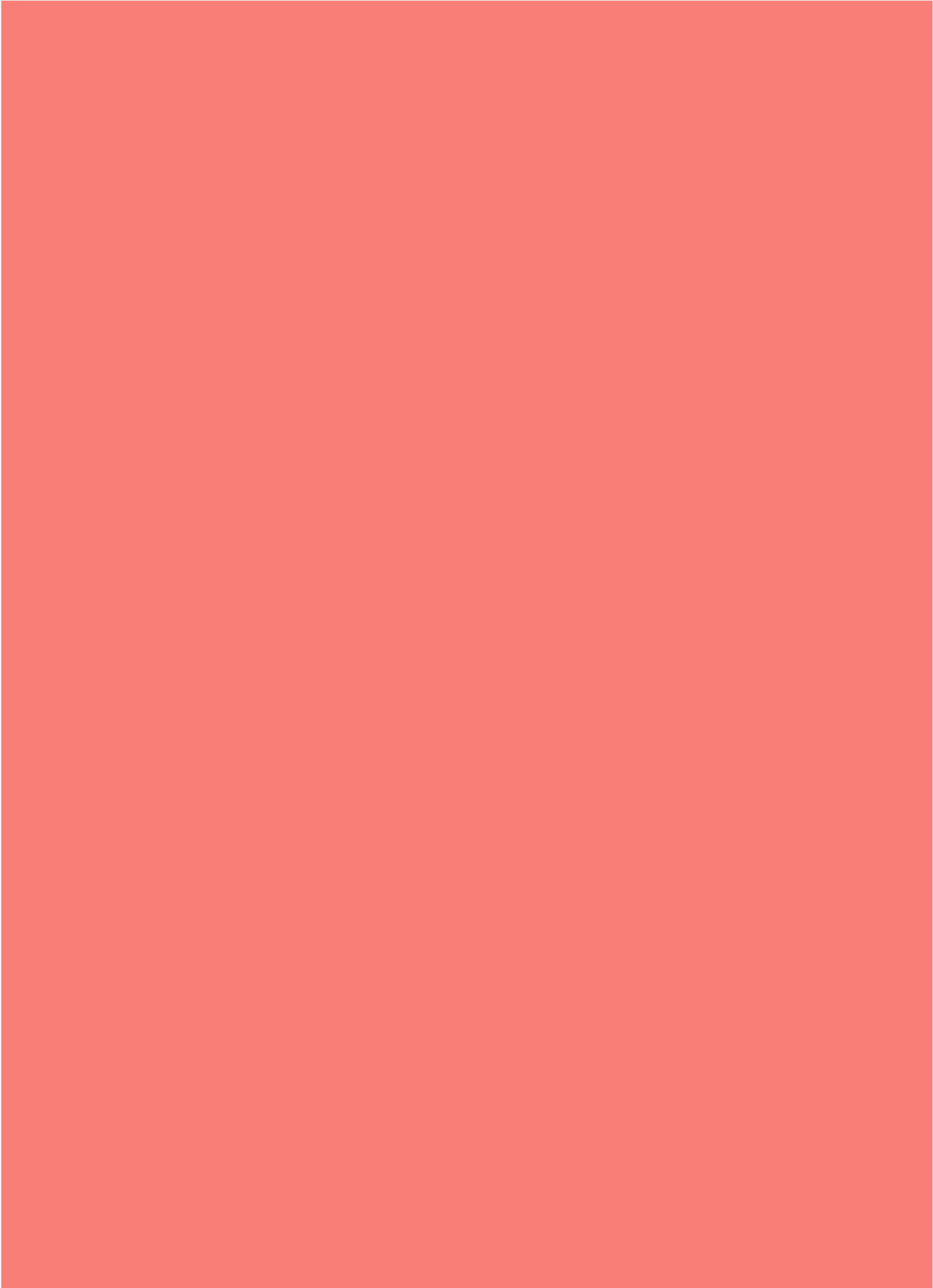
Tutorial Video:



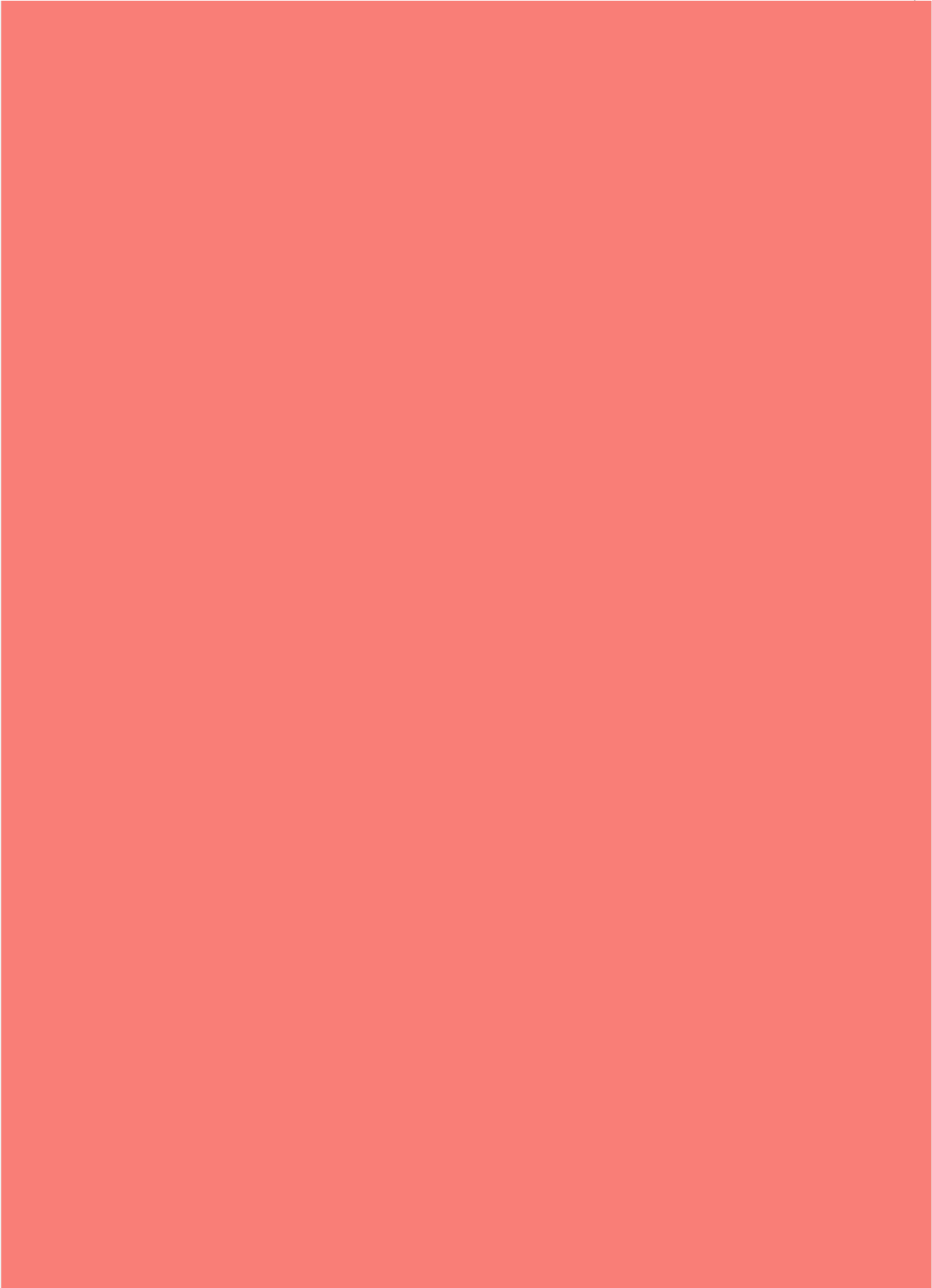
Manas Sharma

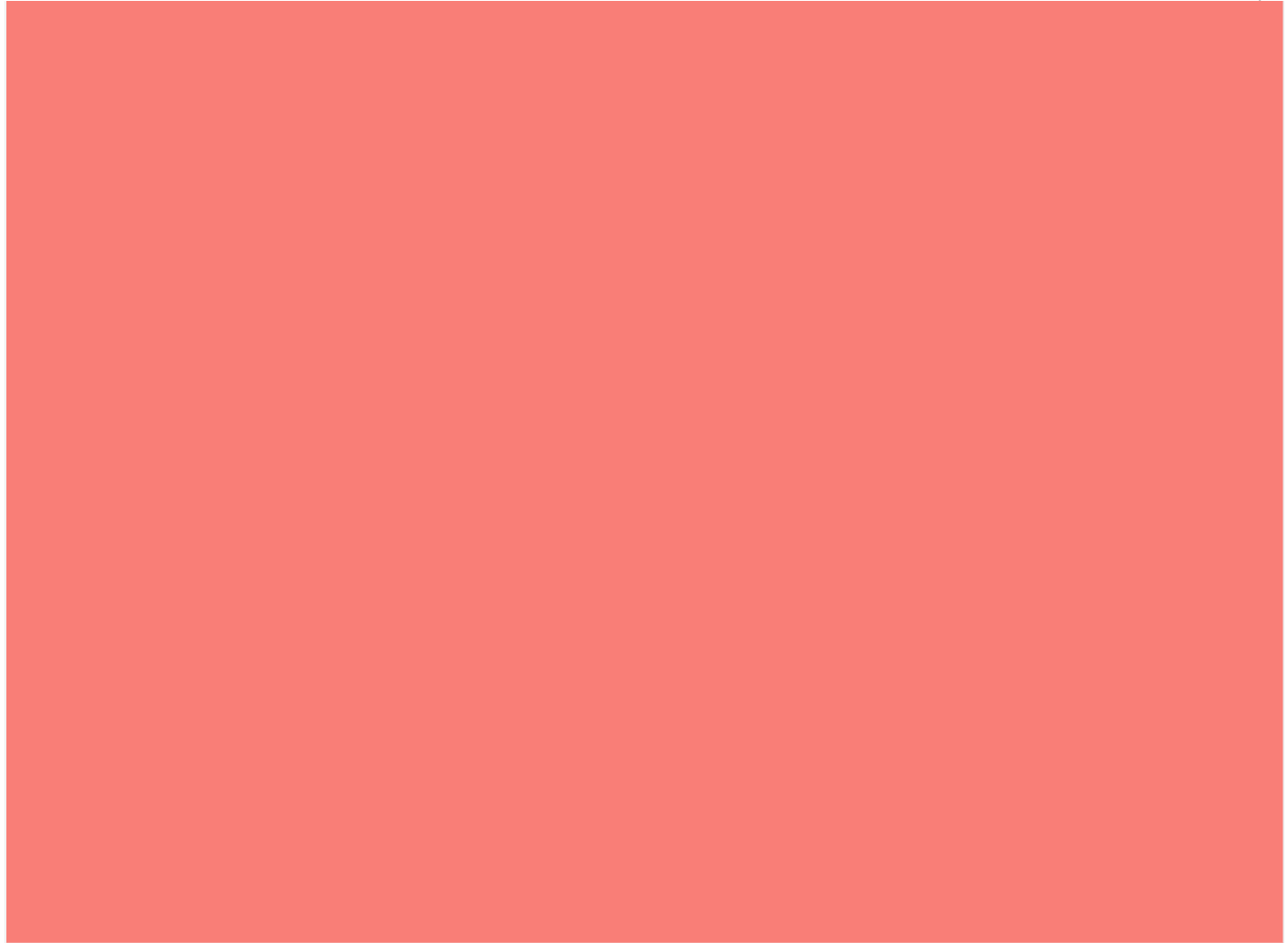
I'm a physicist specializing in computational material science with a PhD in Physics from Friedrich-Schiller University Jena, Germany. I write efficient codes for simulating light-matter interactions at atomic scales. I like to develop Physics, DFT, and Machine Learning related apps and software from time to time. Can code in most of the popular languages. I like to share my knowledge in Physics and applications using this Blog and a YouTube channel.

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